

MINEPLANNING2013

3^{er} Seminario Internacional de Planificación Minera



MINE PLANNING FOR AUTONOMOUS HAULAGE SYSTEM

Author: Marcelo A. Navarrete Fernandez
Codelco-Chile
Division Gabriela Mistral



UNIVERSITY OF
ALBERTA

GECAMIN
Conferencias para la Minería

Celebrando 15 años

EXECUTIVE SUMMARY

- Codelco Chile, Gabriela Mistral in it's 8th Division operates the largest fleet of autonomous trucks in the world. A fleet of 17 Trucks Model 930E4 AT, Brand Komatsu, allowing to transport 210,000 ton / day of materials.
- The positive development of its performance in its five years of operation of the truck AHS - Performance and Effective Utilization - has allowed to continue its decision by operating the site named Gabriela Mistral to exhaustion of reserves.

GENERAL BACKGROUND

Porphyry copper deposit, its main mineralized body is oxidized in a mineralized zone, mainly Chrysocolla, Black and Atacamite oxides in low presence, deposited under sterile coverage of post mineral gravels with an average thickness of 50 m.



- Reserves of 620 millions/tons, oxides
- Average grade of 0.41% CUT and 0.29% CUS, for a cutoff of 0.2% of CUT.
- Acid fuel consumption of 25.5 kg / t.
- Cells between 6 - 7,5 m with P80 12.7 mm (1/2 ").
- Metallurgical extraction averaged 77.2%
- Potential production capacity of 170 ktpa of fine copper in cathode electro-obtained.
- Mina Movement 76 Mton / year
- Lifespan until 2024

MINE PROCESS

Pre-stripping: Ago-06/Jul-07 31 Mth

Mine
 Length : 2.700 m
 Width : 1.700 m
 Prof. : 290 m

Distance Media Crushing
 Primario 3,2 Km.

Width Bench. transport
 28 mts

High bench
 15m

Berm width
 8m

Ramp width
 35m

Average Distance
 Botaderos 3.1 Km.

MINERAL
 620 Mts – 0,41 % CuT
 CRISOCOLA - ATACAMITE- BLACK OXIDE



TRUCK AHS 330tc
 17 unidades



SHOVEL 73 yd³
 2 unidades



DRILLER
 4 unidades



FRONT LOADER
 2 unidades



TRUCK TIRE
 5 unidades



TRUCK Oruga
 3 unidades



BACKHOE
 1 unidad



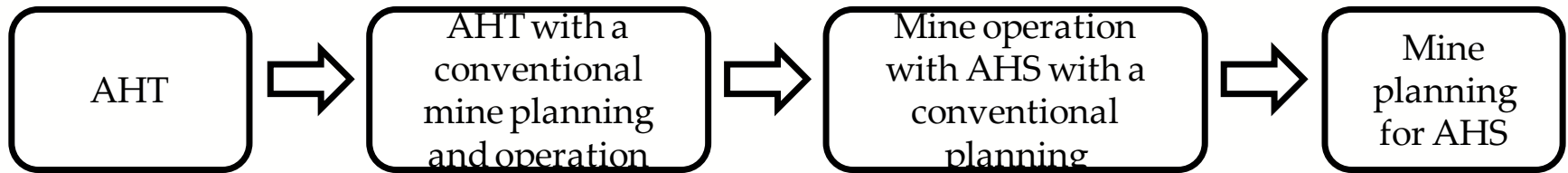
WATER TRUCK
 3 unidades



MOTORNIVELATOR
 3 unidades

METHODOLOGY

- The operation of the AHS CAEX, and their interaction with the rest of the unit operations of the mine, mine planning states must incorporate variables of technology and performance. Achieving an Operation Planning for an Autonomous Trucks.
- Evolution of the Operation and Planning



Layout of the Mine.

Dimensional survey routes, allows to obtain widths and profiles that maximize performance.

Curves consider turning radii.

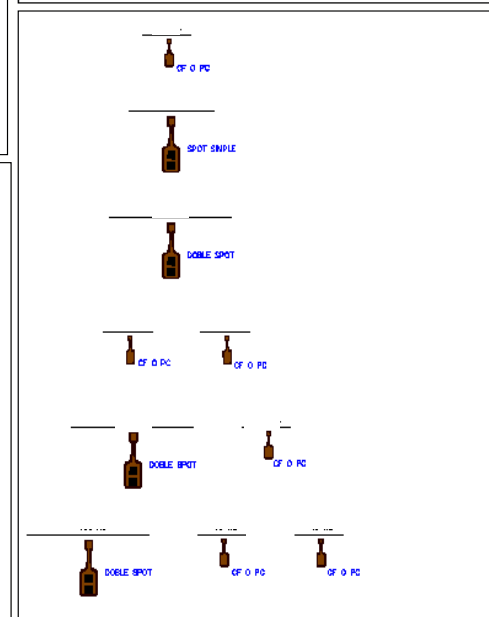
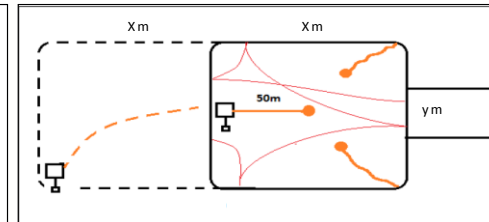
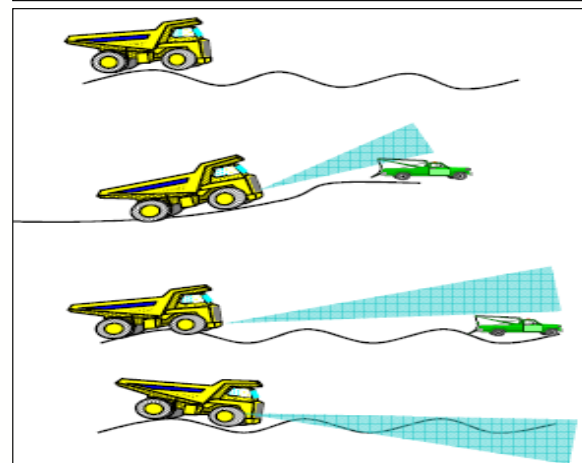
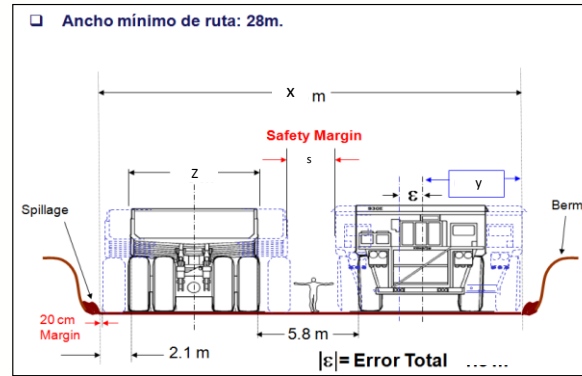
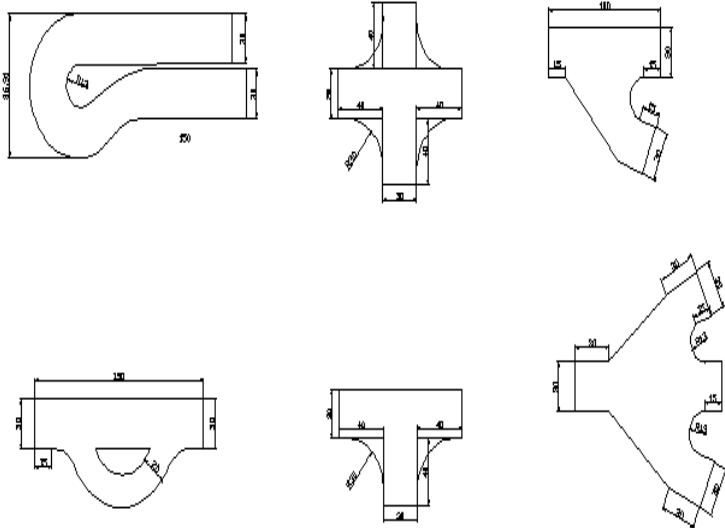
Speed control.

Continuous improvement of the mine design.

AHS OPERATIVE PLANNING

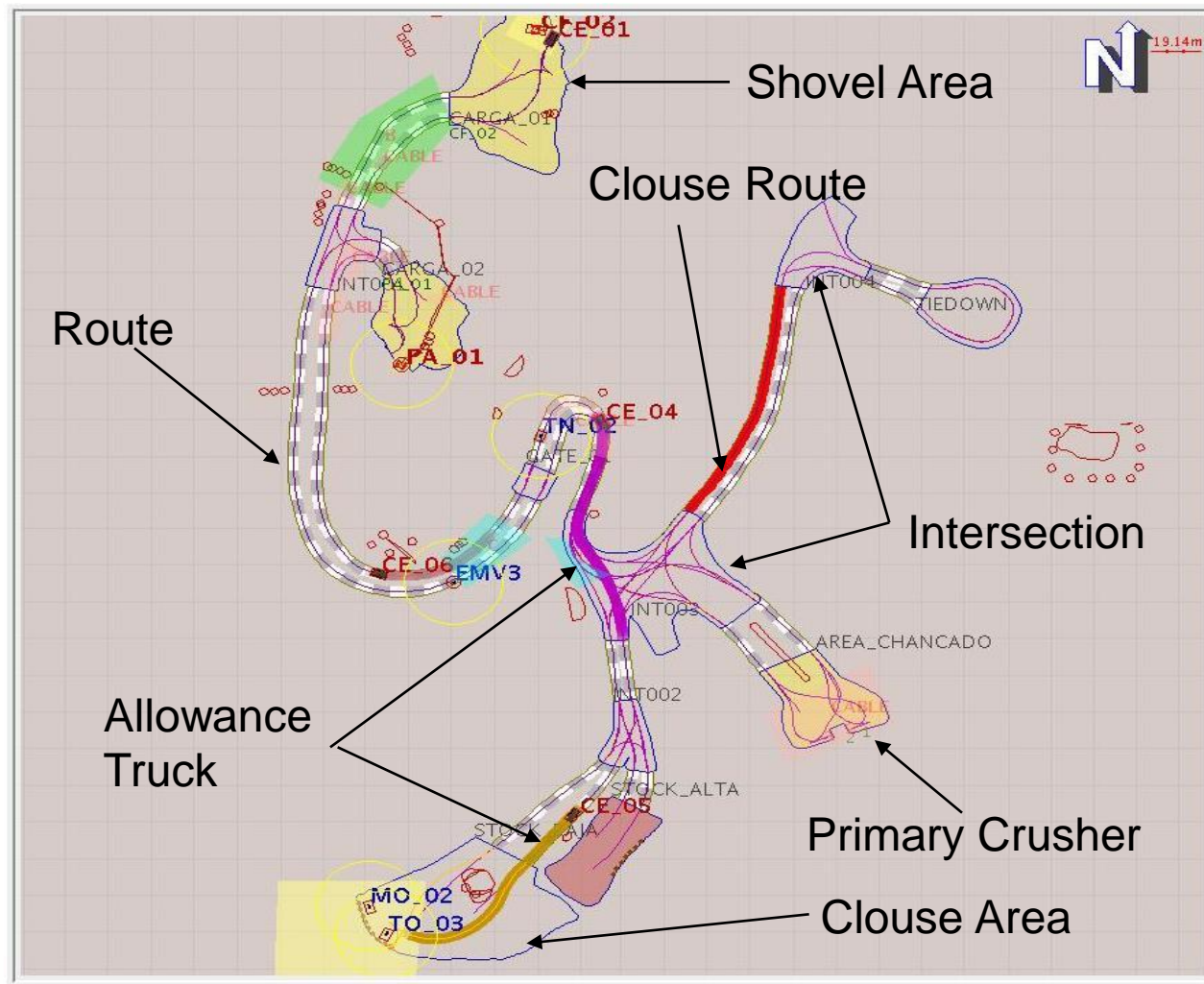
- DESIGN VARIABLES

AHT route design parameters



AHS OPERATIVE PLANNING

OPERATING SYSTEM OF TRANSPORT ROUTES



CONCLUSIONS

- The production associated with trucks transporting materials is directly related to autonomous mine design, and implementation in the field. Incorporate technology variables, the understanding of this and form a multidisciplinary team should be considered.
- The back analysis of the results allows us to understand the behavior of the truck in different operating scenarios.
- The analyzes allows timely to take decisions regarding the correct mine in the different designs to meet production commitments.

FUTURE STEPS

- Stochastic variable Incorporation in mine planning, which allows to obtain a better accurate production based on different scenarios or mine layout.
- Incorporation of AHS events that allows a better accurately plan the use of autonomous trucks based on different designs of the mine.
- Dynamic assignment of autonomous trucks.